

4.1

cost minimization: useful both for competitive and for non-competitive firms

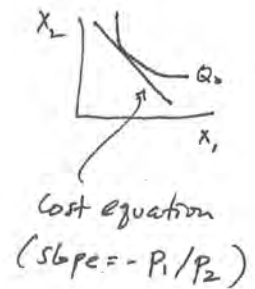
$$c(w, \hat{y}) = \min_{\tilde{x}} w \cdot \tilde{x} \text{ s.t. } f(\tilde{x}) = \hat{y} \quad \mathcal{L} = w \cdot \tilde{x} - \lambda [f(\tilde{x}) - \hat{y}]$$

$$\text{F.O.C. } \tilde{w} = \lambda \nabla_x f \quad \text{or} \quad \frac{w_i}{w_j} = \frac{\partial f / \partial x_i}{\partial f / \partial x_j}$$

↑ TRS

If $\frac{w_i}{w_j} = \frac{z}{1}$ and $\frac{1}{1} = \frac{\partial f / \partial x_i}{\partial f / \partial x_j}$ then

$\left. \begin{array}{l} i \downarrow \text{ by } 1 \\ j \uparrow \text{ by } 1 \end{array} \right\} \begin{array}{l} f \text{ unchanged} \\ \text{costs } \downarrow \text{ by } \$1 \end{array}$



S.O.C. $\Delta x^T \nabla^2 f \Delta x \leq 0$ if Δx satisfying $w \cdot \Delta x = 0$. (over \rightarrow)
(to next section)

↑ not Δ - don't emphasize

... Why the firm has no budget constraint...

4.2

§7.2 $m = 1$ constraint

$n = 2, 3, \text{etc.}$ factors

Start w/ the principal minor of $\nabla^2 \mathcal{L}$ of order $2m+1 = 3$.

$$\begin{bmatrix} \downarrow \\ 0 \\ \hline \end{bmatrix}$$

For a cost minimum: all determinants following should have

$$\text{the sign of } (-1)^m = -1 < 0.$$

4.3

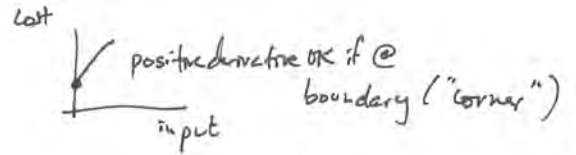
cf §2.2 on differentiable π -max

Difficulties w/ cost-minimization:

1) prodⁿ functⁿ may not be differentiable (e.g. Leontief)

2) $\lambda \frac{\partial f}{\partial x_i} - w_i \leq 0$ if $x_i^* = 0$

$\quad \quad \quad = 0$ if $x_i^* > 0$.



3) existence - not a problem

$\underline{w} \cdot \underline{x} \quad , \quad V(y)$

continuous closed

bounded? Pick an arbitrary $\underline{x}' \in V(y)$.

Instead of considering all $\underline{x} \in V(y)$, only consider

$\{ \underline{x} \in V(y) : \underline{w} \cdot \underline{x} \leq \underline{w} \cdot \underline{x}' \}$.

Upper limit on expenditures (like a budget constraint)

4) nonuniqueness (not a problem if $V(y)$ is convex)

well... need isoquants to be strictly convex



4.4

$$\left. \begin{aligned} f(\underline{x}) &= y \\ \lambda \nabla f(\underline{x}) &= \underline{w} \end{aligned} \right\} \text{F.O.C.'s}$$

$$\nabla f \cdot d\underline{x} = dy$$

$$\nabla f \cdot d\lambda + \lambda \nabla^2 f \cdot d\underline{x} = d\underline{w}$$

$$\begin{bmatrix} 0 & (\nabla f)^T \\ \nabla f & \lambda \nabla^2 f \end{bmatrix} \begin{bmatrix} d\lambda \\ d\underline{x} \end{bmatrix} = \begin{bmatrix} dy \\ d\underline{w} \end{bmatrix}$$

$\uparrow \nabla^2 \mathcal{L}$

$$\Rightarrow \begin{bmatrix} d\lambda \\ d\underline{x} \end{bmatrix} = \begin{bmatrix} \nabla^2 \mathcal{L} \end{bmatrix}^{-1} \begin{bmatrix} dy \\ d\underline{w} \end{bmatrix}$$

symmetric (both $\nabla^2 \mathcal{L}$
and its inverse)

This section does treat $d\lambda$ and dy as well as $d\underline{x}$ and $d\underline{w}$, but otherwise it's less useful than §5.6.

This section does F.O.C. \Rightarrow comp. stat. §5.6 uses duality to get comp. stat. So just do a 2-input example here.

Min $w_1 x_1 + w_2 x_2$ st. $x_1^{1/4} x_2^{3/4} \geq y$.
Find $\partial x_1 / \partial w_2$.

Omit or do briefly.
- Spring 2004

Varian calls \square in $d\underline{x} = \square d\underline{w}$ "the substitution matrix."

This is the $n \times n$ matrix in the lower right of $[\nabla^2 \mathcal{L}]^{-1}$.

4.5

$$(y^t, \tilde{w}^t, \tilde{x}^t), t=1, 2, \dots, T.$$

\uparrow output \uparrow input prices \uparrow inputs

Weak Axiom of Cost Minimization:

$$\forall y^s \geq y^t, \tilde{w}^t \cdot \tilde{x}^t \leq \tilde{w}^t \cdot \tilde{x}^s$$

\swarrow could have chosen \tilde{x}^s at time t \uparrow time t prices

Skip.

- Winter 1996.

Suppose $y^t = y^s$ (??). Then

$$\text{time } t: \tilde{w}^t \cdot \tilde{x}^t \leq \tilde{w}^t \cdot \tilde{x}^s$$

$$\text{time } s: \tilde{w}^s \cdot \tilde{x}^s \leq \tilde{w}^s \cdot \tilde{x}^t$$

$$\Leftrightarrow -\tilde{w}^s \cdot \tilde{x}^t \leq -\tilde{w}^s \cdot \tilde{x}^s$$

add

↓

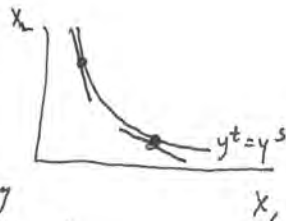
$$(\tilde{w}^t - \tilde{w}^s) \cdot \tilde{x}^t \leq (\tilde{w}^t - \tilde{w}^s) \cdot \tilde{x}^s$$

$$(\tilde{w}^t - \tilde{w}^s) (\tilde{x}^t - \tilde{x}^s) \leq 0$$

Component of 2.5,
WAPM,
 $\Delta p \cdot \Delta y \geq 0$

$$\dots \dots \dots \Delta \tilde{w} \cdot \Delta \tilde{x} \leq 0.$$

But you know this before:



(Except here you needn't put any conditions on the technology.)