

4.1

cost minimization: useful both for competitive and for non-competitive firms

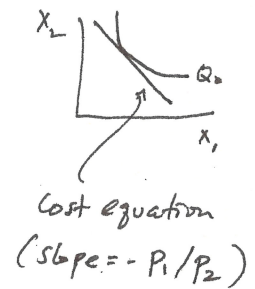
$$c(w, \hat{y}) = \min_{\tilde{x}} w \cdot \tilde{x} \text{ s.t. } f(\tilde{x}) = \hat{y} \quad \mathcal{L} = w \cdot \tilde{x} - \lambda [f(\tilde{x}) - \hat{y}]$$

$$\text{F.O.C. } \tilde{w} = \lambda \nabla_x f \quad \text{or} \quad \frac{w_i}{w_j} = \frac{\partial f / \partial x_i}{\partial f / \partial x_j}$$

↑  
TRS

If  $\frac{w_i}{w_j} = \frac{z}{1}$  and  $\frac{1}{1} = \frac{\partial f / \partial x_i}{\partial f / \partial x_j}$  then

$\left. \begin{array}{l} i \downarrow \text{ by } 1 \\ j \uparrow \text{ by } 1 \end{array} \right\} \begin{array}{l} f \text{ unchanged} \\ \text{costs } \downarrow \text{ by } \$1 \end{array}$



S.O.C.  $\Delta x^T \nabla^2 f \Delta x \leq 0 \quad \forall \Delta x \text{ satisfying } \tilde{w} \cdot \Delta x = 0$  (over  $\rightarrow$ )  
(to next section)

↑  
not  $\leq$  - don't emphasize

Why the firm has no budget constraint...

4.2

§7.2  $m = 1$  constraint

$n = 2, 3, \text{etc.}$  factors

Start w/ the principal minor of  $\nabla^2 \mathcal{L}$  of order  $2m+1 = 3$ .

$$\begin{array}{c} \downarrow \\ \left[ \begin{array}{c|c} 0 & \\ \hline & \end{array} \right] \end{array}$$

For a cost minimum: all determinants following should have

the sign of  $(-1)^m = -1 < 0$ .

4.3

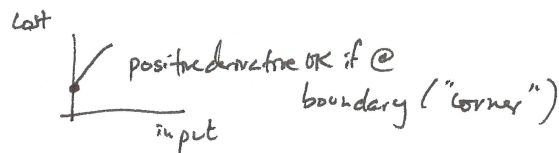
cf § 2.2 on difficulties of  $\pi$ -max

Difficulties w/ cost-minimization:

1) prod<sup>n</sup> fact<sup>n</sup> may not be differentiable (e.g. Leontief)

2)  $\lambda \frac{\partial f}{\partial x_i} - w_i \leq 0$  if  $x_i^* = 0$

$\quad \quad \quad = 0$  if  $x_i^* > 0$ .



3) existence - not a problem

$\underline{w} \cdot \underline{x} \quad , \quad V(y)$

continuous closed

bounded? Pick an arbitrary  $\underline{x}' \in V(y)$ .

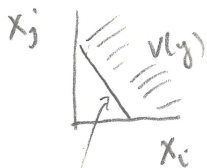
Instead of considering all  $\underline{x} \in V(y)$ , only consider

$\{ \underline{x} \in V(y) : \underline{w} \cdot \underline{x} \leq \underline{w} \cdot \underline{x}' \}$ .

Upper limit on expenditures  
(like a budget constraint)

4) nonuniqueness (not a problem if  $V(y)$  is convex)

well... need isoquants to be strictly convex



Isoquant

4.4

$$\left. \begin{aligned} f(\underline{x}) &= y \\ \lambda \nabla f(\underline{x}) &= \underline{w} \end{aligned} \right\} \text{F.O.C.'s}$$

$$\nabla f \cdot d\underline{x} = dy$$

$$\nabla f \cdot d\lambda + \lambda \nabla^2 f \cdot d\underline{x} = d\underline{w}$$

$$\begin{bmatrix} 0 & (\nabla f)^T \\ \nabla f & \lambda \nabla^2 f \end{bmatrix} \begin{bmatrix} d\lambda \\ d\underline{x} \end{bmatrix} = \begin{bmatrix} dy \\ d\underline{w} \end{bmatrix}$$

$\uparrow \nabla^2 \mathcal{L}$

$$\Rightarrow \begin{bmatrix} d\lambda \\ d\underline{x} \end{bmatrix} = \begin{bmatrix} \nabla^2 \mathcal{L} \end{bmatrix}^{-1} \begin{bmatrix} dy \\ d\underline{w} \end{bmatrix}$$

symmetric (both  $\nabla^2 \mathcal{L}$   
and its inverse)

This section does treat  $d\lambda$  and  $dy$  as well as  $d\underline{x}$  and  $d\underline{w}$ , but otherwise it's less useful than §5.6.

This section does F.O.C.  $\Rightarrow$  comp. stat. §5.6 uses duality to get comp. stat. So just do a 2-input example here.

Min  $w_1 x_1 + w_2 x_2$  st.  $x_1^{1/4} x_2^{3/4} \geq y$ .  
Find  $\partial x_1 / \partial w_2$ .

Omit or do briefly.  
- Spring 2004

Varian calls  $\square$  in  $d\underline{x} = \square d\underline{w}$  "the substitution matrix."

This is the  $n \times n$  matrix in the lower right of  $[\nabla^2 \mathcal{L}]^{-1}$ .

4.5

$$(y^t, \tilde{w}^t, \tilde{x}^t), \quad t=1, 2, \dots, T.$$

$\begin{matrix} \uparrow & & \uparrow \\ \text{output} & & \text{inputs} \\ & \uparrow & \\ & \text{input prices} & \end{matrix}$

Weak Axiom of Cost Minimization:

$$\forall y^s \geq y^t, \quad \tilde{w}^t \cdot \tilde{x}^t \leq \tilde{w}^t \cdot \tilde{x}^s$$

$\begin{matrix} \swarrow & & \uparrow \\ \text{could have} & & \text{time } t \text{ prices} \\ \text{chosen } \tilde{x}^s & & \\ \text{at} & & \\ \text{time } t & & \end{matrix}$

Skip.  
- Winter 1996.

Suppose  $y^t = y^s$  (??). Then

time t:  $\tilde{w}^t \cdot \tilde{x}^t \leq \tilde{w}^t \cdot \tilde{x}^s$

time s:  $\tilde{w}^s \cdot \tilde{x}^s \leq \tilde{w}^s \cdot \tilde{x}^t$

$$\Leftrightarrow -\tilde{w}^s \cdot \tilde{x}^t \leq -\tilde{w}^s \cdot \tilde{x}^s$$

add

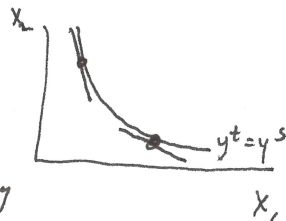
$$(\tilde{w}^t - \tilde{w}^s) \cdot \tilde{x}^t \leq (\tilde{w}^t - \tilde{w}^s) \cdot \tilde{x}^s$$

$$(\tilde{w}^t - \tilde{w}^s) (\tilde{x}^t - \tilde{x}^s) \leq 0$$

Component § 2.5,  
WAPM,  
 $\Delta p \cdot \Delta y \geq 0$

.....  $\Delta \tilde{w} \cdot \Delta \tilde{x} \leq 0.$

But you knew this before:



(Except here you needn't put any conditions on the technology.)